

XGT2/XGL2/XGS2 Flexible coupling - High - gain rubber type Additional Size Patent Pending

- WEB Selection Tool
- WEB CAD Download
- Zero Backlash
- High gain supported
- High torque
- High Rigidity
- Vibration absorption

Structure

Clamping type

- XGT2-C** Standard type → P.xxxx
- XGL2-C** Long type → P.xxxx
- XGS2-C** Short type → P.xxxx



Internal Structure



Servomotor

	XGT2 / XGL2 / XGS2
Servomotor	⊙
Stepping Motor	⊙
General-purpose motor	⊙

⊙: Excellent ○: Very good

Property

	XGT2 / XGL2 / XGS2
Zero Backlash	⊙
For servomotor high gain	⊙
High torque	⊙
High Torsional Stiffness	⊙
Allowable Misalignment	○
Vibration absorption	⊙
Allowable operating temperature	-10°C to 120°C

⊙: Excellent ○: Very good

● High-gain flexible coupling which surpasses of **XGT** **XGL** **XGS** in performance. This is a singlepiece construction with the two aluminum hubs molded with vibration-absorbing rubber.

● He optimal damping and rigidity design enables realization of even greater servomotor gain, leading to a reduction in stabilization time.

→ P.xxxx (Technical Information)

● Suppresses speed unevenness during stepping motor operation. → P.xxxx

● Contributes to improved productivity and quality by suppressing residual vibration during positioning.

● Features outstanding thermal, oil and chemical resistance.

→ P.xxxx (Physical properties and chemical resistance of vibration-absorbing rubber)

● Standard type **XGT2** , Long type **XGL2** and Short type **XGS2** standardized.

Application

Semiconductor manufacturing equipment / Mount machines / Machine tools / Packaging machines

Material/Finish



	XGT2 / XGL2 / XGS2
Hub	A2017
Vibration-absorbing rubber	FKM
Hex Socket Head Cap Screw	SCM435 Ferrosoferric Oxide Film (Black)

Part number specification

XGT2-19C-6-8

Product Code	Size	Bore Diameter
XGT2-19C-6-8	6	8

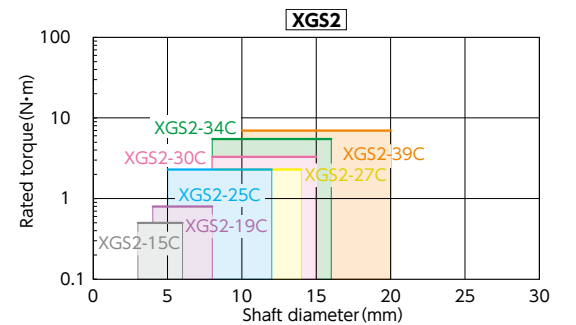
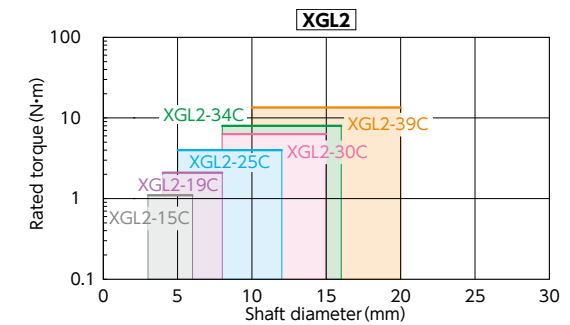
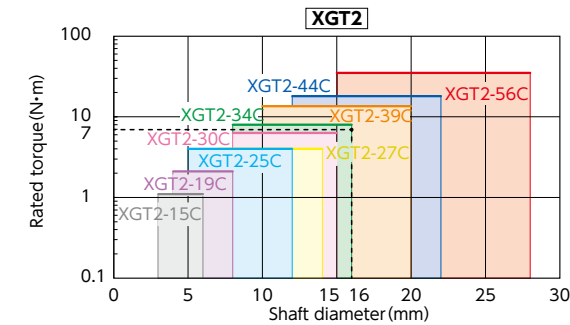
Please refer to dimensional table for part number specification.



Selection

Selection based on shaft diameter and rated torque

The area bounded by the shaft diameter and rated torque indicates is the selection size.



Selection example

In case of selected parameters of shaft diameter of ϕ 16 and load torque of 7N·m, the selection size is

XGT2-34C .

Selection based on the rated output of the servomotor

Rated output (W)	Servomotor specifications*			Selection size		
	Diameter of motor shaft (mm)	Rated torque (N·m)	Instantaneous max. torque (N·m)	XGT2	XGL2	XGS2
10	5 - 6	0.032	0.096	15C	15C	15C
20	5 - 6	0.064	0.19	15C	15C	15C
30	5 - 7	0.096	0.29	19C	19C	19C
50	6 - 8	0.16	0.48	19C	19C	19C
100	8	0.32	0.95	19C	19C	25C
200	9 - 14	0.64	1.9	27C	30C	27C
400	14	1.3	3.8	27C	30C	34C
750	16 - 19	2.4	7.2	39C	39C	-

*Motor specifications are based on general values. For details, see the motor manufacturer's catalogs. This is the size for cases where devices such as reduction gears are not used.

- Additional Keyway at Shaft Hole → P.xxxx Available / Add'l charge
- Cleanroom Wash & Packaging → P.xxxx Available / Add'l charge
- SUS Change to Stainless Steel Screw → P.xxxx Available / Add'l charge