Specifications

FE7W Series

Photoelectric Sensors for Collision Prevention Sensing

FEATURES

Collision of an Automatic Guided Vehicle (AGV) is Prevented in Advance. Obstavles Can be Sensed not in the Forward Direction of the AGV but also in the Left and Right-hand Directions to Reduce the Speed or Stop the AGV.

- The obstacle sensing range can be set to two modes. (slow, stop)
- Obstacles can be sensed not only in the forward direction of the AGV, but also in the left- and right-hand directions. (FE7W-D

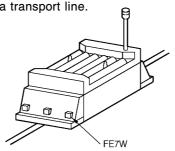
 /5K)
- Mutual interference between carts can be prevented since the signal emission frequency can be selected from 4 or 8 arcs.
- Wide or narrwo detection width can be selected according to the AGV size.
 (FE7W-D□/5K)
- Sensors are compact and easy to adjust from the front.
- Obstacles can be detected from a long 3m range in the direction of travel.
 These sensors are applicable to even high speed AGVs.



■ APPLICATION EXAMPLES

• Preventing the collision of AGVs.

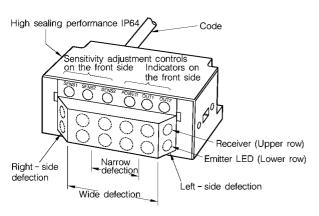
• Sensing long-range position in a transport line.



ORDER GUIDE

Detection method	Shape	Detection	Forward detection width	Operating mode	Output	Catalog listing	
Diffuse scan		2 rows in forward direction and left	1/0.3m	N.O. light operated	NPN Open collector	FE7W-DA5K	
	000000	& right sides (45 degrees)	selection	N.C. dark operated	NPN Open collector	FE7W-DB5K	
		2 rows in forward	0.3m fixed	N.O. light operated	NPN Open collector	FE7W-DA5	
		direction	0.5III lixed	N.C. dark operated	NPN Open collector	FE7W-DB5	

EXTERNAL VIEWS



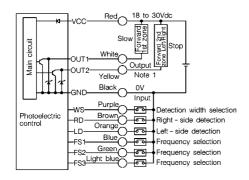
SPECIFICATIONS

Detection method Catalog listing				FE7W	-DA5ł	(FE7W	-DB5K		e scan		N-DA5		FE7W-DB5				
Detection form			Forward (2 rows) and left & right sides (45 degrees)								Forward (2 rows)								
Scanning	Forward: 1st row			3m									3m						
distance	Forward: 2nd row			2.5m											2	.5m			
	Left/right (45 degrees)				1m														
	Standard target object			100000								reflecti	ng par	per					
Sensitivity	Forward: 1st row			SENS 1 control								SENS 1 control							
adjustment	Forward: 2nd row			SENS 2 control								SENS 2 control							
	Left/right (45 degrees)			SENS 3 control								—							
Detection width	<u> </u>				0.3/1.0m selectable by external input								0.3m fixed						
(1st row)	Vertical direction					0.3m fixed								0.3m fixed					
Response speed		our un	odion				0.011	плоа	(nerati	ion re	set: Ma	x 80m	าร	0.01	II IIXOG			
Differential trave										о роган		20%							
Light emitter					Infrared LED														
Supply voltage												30Vdc							
Current consum	ption			Max. 70mA															
Control	· ·					Forward 1st zone output								Forward 1st zone output					
output	OUT 2 (Stop)			Forward 2nd zone and left/right 45 degrees or connection output								Forward 2nd zone output							
	Operating mode			Light operated Dark operated									Light operated Dark operated						
	Output form			· .									collector						
	Output switching current			Max. 100mA (resistive load) with output short-circuit protection circuit OUT 1, 2															
	Output saturation voltage			Max. 1V (when															
ndication	OUT 1			Illuminates (at detection in the 1st zone)								Illuminates (at detection in the 1st zone)							
	OUT 2			Illuminates (at detection in the 2nd or left/right zone)								Illuminates (at detection in the 2nd zone)							
	POWER			Illuminates when power is supplied								Illuminates when power is supplied							
External		t form						•			t (low l	level input voltage: Max. 1.5V)							
control																			
input	Detection width selection	Wide width							_	T									
		Š	NPN:	OUT. 2 OUT. 1 1m															
	sel	/ide	Open WS-GND																
	£	>																	
	ξ	_																	
	on	Narrow width																	
	Ş	>	NPN:	OUT. 2 OUT. 1 0.3m															
)ete	rov	Close WS-GND																
		Nar																	
	Right-side																		
	detection (Right Close RD-GND																		
			Close RD-GND																
			1,45°																
_																			
	Loft	sido					\sim	45°											
	Left-side detection (Left Close LD-GND LED only)		NPN:	45															
							1	45°											
	Right & NPN: left Close RD-GN detection Close LD-GNI		NPN:																
			Close RD-GND																
			Close LD-GND																
							W.	45°											
			Frequency No.	1	2	3	4	5	6	7	8	1	2	3	4				
		<u> </u>	NPN: FS1-GND	0	0							0	0] /			
	_ion	abl	INI IN. I GI-GIND	\square		\perp		_	_		•		\perp	_	_	 			
	issi	ect de t	NPN: FS2-GND		0							0							
	Sig	selection code table				_		\vdash	\vdash			_							
			NPN: FS3-GND		•	0	•	0	•	0		O: (Open	●: S	hort				
Operating ambie	Incandescent lamp: Max. 3,000lux, solar light: Max. 10,000lux																		
Operating temper							11100		iaii			+60°		1414/	10,0				
Storage tempera												+70°							
Humidity range		2.190										35% RI							
Insulation resistance, dielectric strength				Min. 20MΩ (measured with 500Vdc megger), 500Vac 1 minute															
Vibration					Double amplitude 1.5mm, 10 to 55Hz, 2 hours along each of X, Y, Z axes														
Shock Protection Housing					490m/s ² 3 times along each of X, Y, Z axes IP64														
																Polycarbonate Lead length: 2, 10m 9.0mm dia. in diameter 0.3mm ²			
					Lead Weight					Lead length: 2, 10m 9.0mm dia. In diameter 0.3mm ² Approx. 350g									
					Maiah+											Appro	x. 35U(J	

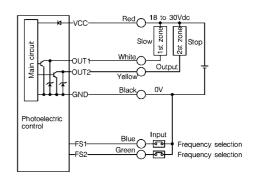
• Installation Instructions No.: CP-UM-3071E

■ WIRING DIAGRAM

• FE7W-DA5K/DB5K

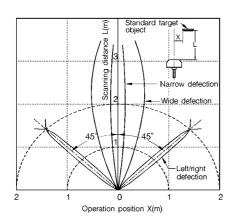


FE7W-DA5/DB5

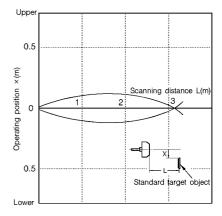


■ CHARACTERISTICS ■

• Detection area characteristics (Horizontal)
Forward (1st row) detection, left/right detection (Sensitivity adjustment control: Maximum)

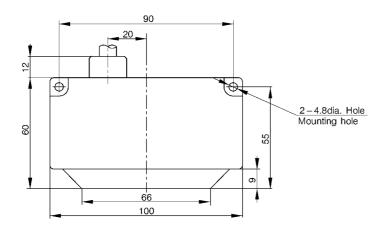


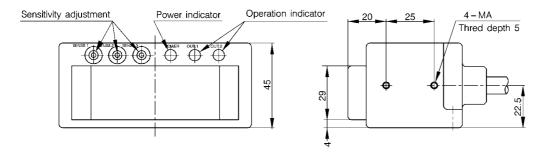
• Detection area characteristics (Vertical)
Forward (1st row) detection (Wide/Narrow; Sensitivity adjustment control: Maximum)



EXTERNAL DIMENSIONS

(unit: mm)

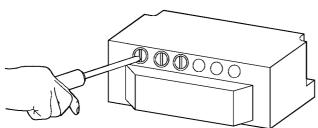




■ BASIC INSTRUCTIONS

• Basic instructions for sensitivity adjustment

- The scanning distance and the detection area of a diffuse scan model depend on the size, material, and reflectance of the target object.
- To adjust the sensitivity, when a target object is present, raise the sensitivity adjustment gradually from minimum and set it where the operating indicator illuminates or where the output toggles.
- · After adjusting the sensitivity, remove the target object and make sure that the indicator goes out without being influence from the background or nearby objects. Check this over the entire motion range of the photoelectric sensor.
- If the background or other nearby objects influence the sensor's sensitivity, reduce the scanning distance or remove the object. Since a white wall exerts a large influence, select dark backgrounds if possible.
- · Since the sensitivity is adjusted on the front side, make sure your hand is not detected during the above adjustments.



Do not influence the defection surface with your hand.

- The sensitivity of the 1st row and the 2nd rows (forward sensing) can be adjusted independently using SENS 1 and SENS 2. You are advised to set the 1st row (which has a long scanning distance) first. After making sure that the background and nearby objects are not exerting any influence, adjust the 2nd row.
- · Only one sensor is provided for adjusting the sensitivity of right-side and left-side detection. The two sides cannot to adjusted independently.
- If you are not using left-right-side detection, set SENS 3 to the minimum

Wiring instructions

- · Connect photoelectric sensors, power units and loads correctly.
- Do not put photoelectric sebsor leads in the same conduit tube as high voltage or power cables. Surges and noise can cause destruction or incorrect operation.
- · Connect the ends of leads securely using a crimp terminal.
- Use a cable of at least 0.3mm². The lead should not be longer than 100m. Consider the influence of noise due to lead extension
- If a generic controlling regulator is used, ground its frame.

Mounting instructions

- · Since this is a long-range diffuse scan photoelectric sensor, take into consideration the reflectance of the background and nearby objects. Pay special attention to reflection from the reflector of a nearby coaxial diffuse scan photoelectric sensor.
- When a number of photoelectric sensors of this series must be used in the same space, set their frequencies by referring to the frequency selection code table, in order to prevent incorrect operation due to mutual interference.
- · Unstable operation may be caused by the signal of another photoelectric sensor. Therefore, carefully study the layout of all controls



RESTRICIONS ON USE

This product has been designed, developed and manufactured for general-purpose application in machinery and equipment. Accordingly, when used in applications outlined below, special care should be taken to implement a fail-safe and/or redundant design concept as well as a periodic maintenance program.

- Safety devices for plant worker protection Start/stop control devices for transportation and material handling machines
- Aeronautical/aerospace machinesControl devices for nuclear reactors

Never use this product in applications where human safety may be put

ΥΛΙΜΔΤΔΚΕ

Specifications are subject to change without notice

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